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Product specification Displacement Transmitter Series DT-120

Axial shaft position

Non-contacting integrated displacement transmitter

Features

- Maximum linear range 2 mm (0.5 2.5 mm from target)
- Loop-powered
- Driver electronics are built into the transmitter housing
- Temperature range: -40 °C ... +105 °C.
- Dynamic signal output for easy installation (raw signal)
- Cost-saving installation no separate driver needed



Measurement

Radial shaft vibration





DT-12x.AP1

Product description

The integrated DT-120 series displacement transmitters are based on the non-contacting eddy current measurement principle, which has proven itself in the machine monitoring sector for several decades. It allows the distance between the tip of the displacement transmitter and an electrically conductive surface to be measured. The integrated electronics measure the axial shaft position or the radial shaft vibration from the displacement signal, depending on the model being used. The measurement result is outputted to a subsequent controller, via the loop-powered interface, as a 4 - 20 mA signal. An additional dynamic output provides a diagnostic signal for simple system setup or signal analysis. Our series DT-120 eddy current displacement transmitters are distinguished by their innovative design. All of the measuring electronics and the loop-powered interface are integrated in the transmitter's housing. This considerably simplifies the installation of these systems as compared to those with external driver electronics. The displacement transmitter is available in both forward and reverse mount versions.

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¹ "x" option defines the housing version

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Technical data

The following performance data applies under the following standard conditions, unless stated otherwise: +18 °C to +27 °C ambient temperature, +24 VDC supply voltage, 250 Ω loop resistance, dynamic output not connected, B&K Vibro original reference material, Material-No. 1.7225 (42CrMo4) as per EN10083-3 and as per AISI/SAE 4140, +6 V gap voltage; all components are at operating temperature (approx. 1h).

Measurement type: Radial Vibration (RV) Axial Position (AP)	Radial shaft vibration in [µm peak-to-peak] Axial shaft position in [µm]
Measuring principle	Eddy current method
Functional characteristics: Loop output: Output signal Signaling (range overshoot, error) System error Full scale range overshoot (RV + AP) Full scale range undershoot (AP only) Loop resistance Nominal Maximal Accuracy 0 °C + 45 °C	4 - 20 mA, live-zero As per NAMUR Recommendation 43 < 3,6 mA 20,5 mA 3,8 mA 250 Ω depends on the supply voltage V _{Loop} (see Fig. 1) ±0,2 % from full scale (FS)
Overall operating temperature range	±0,5 % (FS)
Installation Position Transmitter (GAP):	
Transmitter must be gapped from target (shaft) between equal to linear range	+2V to +18V > 0.5mm to < 2.5mm
Radial shaft vibration (DT-12x.RV): Full scale range, nominal [µm peak-peak] Loop sensitivity, nominal [µm p-p/mA] Full scale range, nominal [mils peak-peak] Loop sensitivity, nominal [mils p-p/mA] Sensitivity accuracy in the temperature range of: 0 °C +45 °C Overall operating temperature range Loop frequency range Loop refresh time	0 - 100 0 - 250 0 - 600 6,25 15,63 37,5 0 - 4 0 - 10 0 - 24 0,25 0,625 1,5 ±5 % ±10 % 5 Hz 4 kHz 15 ms
Axial shaft position (DT-12x.AP): Full scale range, nominal [mm] Loop sensitivity, nominal [µm/mA] Full scale range, nominal [mils] Loop sensitivity, nominal [mils/mA] Accuracy Deviation (DSL) from best fit straight line with nominal loop sensitivity in the temperature range of: 0 °C +45 °C Overall operating temperature range Loop frequency range Loop refresh time	0 – 1,2 0 – 1,5 75,0 93,8 0 – 50 0 – 60 3,125 3,75 ±25 µm ±75 µm DC 0,8 Hz 100 ms

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Dynamic output:	
Application	Connection of a potential-free portable measuring instrument for system setup or signal analysis; not designed for continuous operation; limited cable length
Cable length	max. 15 m
Cable capacity Output resistance Output signal Sensitivity, nominal	(including transmitter integrated cable length) max. 150 pF/m 8 k Ω DC (load > 500 k Ω , 1,5 nF) Depends on the loop voltage and loop resistance, see Table 1 +8 mV/um
Frequency range	DC 8 kHz (-3 dB output signal damping)
O °C +45 °C Overall operating temperature range Behaviour in the event of maximum linear range overshoot or system error	±5 % ±10 % Output remains active; max. output voltage depends on loop voltage; short voltage dips at the start of signaling of a measuring range overshoot is possible short circuit proof and miswiring proof
Electrical properties:	short circuit proof and miswining proof
Operating voltage Current consumption	+24 VDC (+12 VDC +32 VDC) max. 21 mA
Mechanical properties:	
Cable: Design Cable sheath and colouring Wire assignments: Loop Dynamic output Diameter Wire cross-section Length	4 wire PTFE, black white (+), black (-) red (+), blue (-) Ø 2,9 mm (±0,15 mm) 0,16 mm ² 5 m or 10 m
Transmitter tin:	
Material Tip diameter	Ceramic Ø 7,2 mm (± 0,1 mm)
Transmitter sleeve:	
Material Recommended tightening torque Transmitter weight (5m version):	Stainless steel (Material-No.1.4404 X2CrNiMo17-12-2 nach EN10088-3) 5 Nm approx. 150 g
Environment:	
Pressure tightness:	
Transmitter tip Transmitter with corrugated tube protection	25 bar 25 bar (valid only for DT-122)
Operating temperature range Storage temperature range	-40 °C +105 °C -55 °C +125 °C IP68 IP69
in protection degree according to EN 00329	11 00, 11 09



Notes on operation

Maximum loop resistance R Loop-max

The total loop resistance consists of the measuring resistance of the supplying electronics and the effective cable resistance:

• R Loop = R Meas + R Cable

The maximum permissible loop resistance for a given voltage supply V $_{Loop}$ is calculated using the following formula:

• R Loop-max = 47 x (V Loop - 12) [Ohm]

R-Loop-max (Ohm) 1000 750 500 250 Operating area

The diagram shows the relationship between the supply voltage V $_{Loop}$ and the maximum permitted loop resistance.

Figure 1) Dependency of the supply voltage on the maximum loop resistance

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Range of the maximum dynamic output signal

0 12

The output of the diagnostic signal via the dynamic output DYN_OUT requires a sufficiently high supply voltage V $_{Loop}$ for a given loop resistance R $_{Loop}$:

24

28

Supply voltage V Loop (Volt)

32

36

DYN OUT < V Loop - I Loop x R Loop - 2.6 V

Table 1) shows the relationships between the maximum outputted DYN_OUT and R Loop and V Loop

20

	R _{Loop}			
V _{Loop}	100 Ω	250 Ω	500 Ω	
20 V	15.4 V	12.4 V	1)	
24 V	19.4 V	16.4 V	11.4 V	
28 V	21.4 V ²⁾	20.4 V	15.4 V	
Table 1) DVN		an V (a an)		

 Table 1)
 DYN_OUTMax (R Loop, V Loop)

1) No operation possible

2) Voltages higher than 21.4 V cannot be outputted.

In case of insufficient supply voltage V LOOP, the DYN_OUT dynamic output signal range might be limited.





Clearances and minimum distances

The clearances and minimum distances specified below must be observed when installing the transmitter.





Mechanical versions²

Displacement transmitter with continuous thread DT-121...

- Without cable protection: DT-121.MT/MR/TT/LLL/UUU/PPP/000/R (upper image)
- With steel protective conduit, Length XX: *DT-121.MT/MR/TT/LLL/UUU/PPP/2XX/R* (centre image)
- With PTFE protective conduit, Length XX: *DT-121.MT/MR/TT/LLL/UUU/PPP/3XX/R* (lower image)



Displacement transmitter with continuous thread and pressure-tight corrugated tube DT-122...

- With corrugated tube protection design A, Length XX: *DT-122.MT/MR/TT/LLL/UUU/PPP/***4XX**/*R* (upper image)
- With corrugated tube protection design B, Length XX: *DT-122.MT/MR/TT/LLL/UUU/PPP/5XX/R* (lower image)



² Comments about drawings: all information is in [mm]

Displacement transmitter for reverse mount DT-123...

- Without cable protection DT-123.MT/MR/TT/073/013/PPP/000/R (upper image)
- With steel protective conduit, Length XX: *DT-123.MT/MR/TT/073/013/PPP/2XX/R* (centre image)
- With PTFE protective conduit, Length XX: *DT-123.MT/MR/TT/073/013/PPP/3XX/R* (lower image)





Displacement transmitter order code

DT-12D.MT / MR / TT / LLL / UUU / PPP / CXX / R

	DT-121	DT-122	DT-123	DT-12
"D" transmitter type				D
Continuous thread	\checkmark			1
Continuous thread with corrugated tube		V		2
Reverse mount			V	3

"MT" Measurm	ent type			.MT
Radial shaft vibration (RV)		V		RV
Axial shaft position (AP)			V	AP
"MR" Measuring Range	-			 / MR
		100	1.2	0
RV [µm] / AP [mm]		250	1.5	1
		600		2
		4	50	5
RV [mils] / AP [mils]		10	60	6
		24		7
"T" Threa	ad			/ TT
M10 x 1		V	V	10
3/8 – 24 UNF-2A		V	V	62

				>
"L" Length of the transmitter body [mm] Increment 005 = 5 mm				/ LLL
Preferred lengths	75	75		075
	90	90		090
	105	105		105
	125	125		125
Fixed length			73	073
Other lengths min - max	75 - 250	75 - 250		XXX

	DT-121	DT-122	DT-123	DT-12
"U" unthreaded section [mm] $U_{max} = L - 40 \text{ mm}$; increment '005' = 5 mm (a Distance measured from tip of transmitter to r	as from "U" = non-threaded	15 mm) section		/ UUU
Preferred length	15	15		015
Fixed length			13	013
Other lengths min - max	20 - 210	20 - 210		XXX
"P" Length of the integrated cable [dm]				/ PPP
	5.0	5.0	5.0	050
	10.0	10.0	10.0	100
"CXX" Cable protection for integrated cable The minimum length is ' $05' = 0,5$ m with fixed CXX = ' $000'$ means "no protection" and XX = protection for the transmitter version (the protection end of the cable).	l e [dm] increments '99' for maxi ection ends	of 0.1 m. mum possible approx. 0.4 m	e cable I from the	/ CXX
No protection	V		V	000
Steel protective conduit	V		V	2XX
PTFE protective conduit	V		V	3XX
Corrugated tube protection, design A		V		4XX
Corrugated tube protection, design B		V		5XX
"R" Special requirements				/ R
No	V	V	V	0
Yes (need to be put in writing)	Upon request		1	

Accessories

AC-2140: two channel connection module



Order example



Approval / Declaration of Conformity

Displacement transmitter systems are:

CE Conformity as per EMC Directive
EN 61326-1: 2013
EN 50581: 2012

RCM for Australia and New Zeeland

CE



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Product specification Transmitter Series DT-120

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